

# Reinforcement Learning for Long-Horizon Multi-Turn Search Agents



Vivek Kalyan research@vivekkalyan.com

Martin Andrews martin@redcatlabs.com



## **Motivation**

### Goal

Solve complex legal search tasks where answer requires navigating massive corpora over multiple turns

### **Problem**

Prompt-based agents often stall or hallucinate in long-horizons searches

### **Solution**

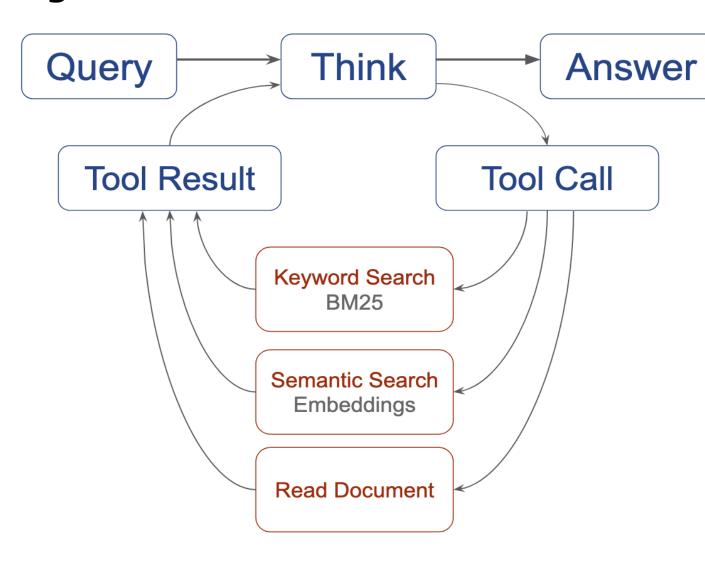
Treat multi-turn search as a Reinforcement Learning problem. Train a model using verifiable rewards ("did the model find the right document?")

### **Outcome**

Outperform frontier models by training Qwen3-14B: 85% vs 81%

# **Method and Results**

### **Agent Architecture**



### Reward

1 to 2 Correct answer

0 to 1 "I don't know"

-1 to 0 Wrong answer

-2 to -1 Formatting errors

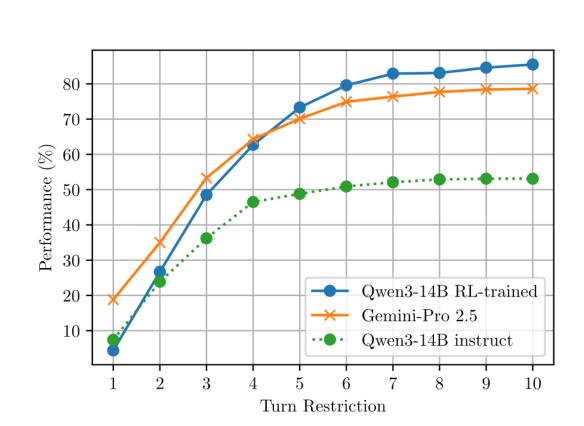
Prefer "I don't know" when unable to find sufficient evidence to hallucination

Model	Accuracy (%)	Avg. Turns
Naïve RAG (Gemini 2.5 Pro)	33	1.0
Qwen3-14B (base)	53	3.7
Gemini 2.5 Flash	66	3.4
Gemini 2.5 Pro	78	5.3
OpenAI o3	81	7.1
Qwen3-14B + RL	85	6.2

# **Multi-Turn Experiments**

### **Turn-restricted inference**

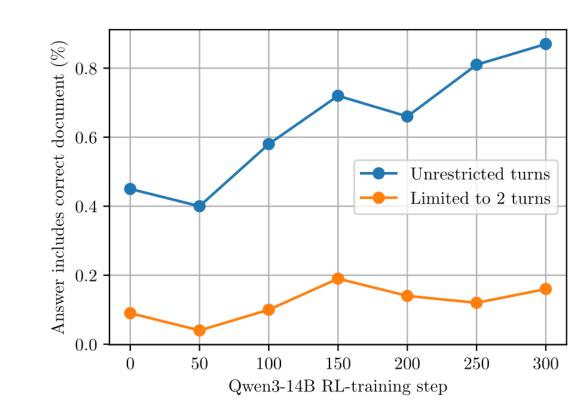
"Does doing more turns improve agent performance?"



All models improve with more turns, but RL-trained Qwen3-14B continues to gain where others plateau

### **Turn-restricted training**

"Is Long-Horizon Training Necessary for Multi-Turn Success?"



Training with ≤ 2 turns prevent the agent from discovering effective long-horizon policies

# Discussion

RL turns multiple turns into actual capability: with the same tools and horizon, Qwen3-14B + RL converts additional turns into higher accuracy than both the base model and frontier APIs.

Long-horizon experience is essential: restricting the number of turns during training causes agents to fail on longer-horizon tasks, suggesting that horizon mismatch is a key failure mode for multi-turn agents.

For search, this is a repeatable playbook to create grounded agents

# **Key References**

- "Retrieval-augmented generation for knowledge-intensive NLP tasks"
  Lewis et al (2020)
- ▲ "DeepSeekMath: Pushing the limits of mathematical reasoning in open language models" Shao *et al* (2024)
- ▲ "ART: Agent Reinforcement Trainer" Hilton *et al* (2025) https://github.com/openpipe/art

# Contact



vivekkalyansk

mdda123